		STUDY MODULE D	ESCRIPTION FORM		
Name Con	of the module/subject I trol theory		Code 1010332211010331168		
Field o	f study		Profile of study (general academic, practical)	Year /Semester	
Automatic Control and Robotics			general academic	1/1	
Elective path/specialty			Subject offered in: Polish	Course (compulsory, elective) obligatory	
Cycle of study:			Form of study (full-time,part-time)		
Second-cycle studies			full-time		
No. of	hours			No. of credits	
Lecture: 45 Classes: - Laboratory: -			Project/seminars: 15	5	
Status	of the course in the study	/ program (Basic, major, other) other	(university-wide, from another field univers	sity-wide	
Educat	tion areas and fields of so	ience and art		ECTS distribution (number and %)	
tech	nical sciences			5 100%	
Technical sciences				5 100%	
Wy ul. Prere	rdział Elektryczny Piotrowo 3A 60-965 P equisites in tern	oznań n s of knowledge, skills an Knowledge of algebra, basics of	d social competencies: f probability theory and control the	ory for continuous systems.	
1	Knowledge				
2	Skills	is able to use mathematical app	aratus of algebra and set theory.		
3	Social competencies	Readiness to work in groups an	d ability to solve problems current	ly unknown to the student.	
Assu	imptions and ob	jectives of the course:			
Impro discre	vement of theoretical a te and continuous dyr	and practical skills related to mode namics).	Iling of discrete event systems and	d hybrid systems (with	
Updat learnii	e 2017: Gaining comp ng.	etences in coping with uncertainty	in control system through the use	of elements of machine	
	Study outco	omes and reference to the	educational results for a	field of study	
Kno	wledge:				
1. Has Skill	s organized and exten	ded knowledge on design and ana	Ilysis of control systems [K_W02	2]	
1. Is a roboti	ble to determine mode cs systems [K U04]	els of compound systems and proc	cesses and to use them to analyse	and design automation and	
Soci	al competencies	:			
1. Is able to think and act in creative and entrepreneurial manner [K_K05]					
		• · · ·			
		Assessment metho	ds of study outcomes		

Written examination, tests written/oral, projects.

Course description

Lectures: Introduction to discrete event systems, languages and automata; operations on automata; finite state automata; analysis of discrete event systems; supervisory control

timed and hybrid models; stochastic automata with time; Petri Nets -- analysis and applications; Markov chains;

Update 2007: Markov Decision Processes; Elements of Machine Learning.

Projects: preparation to simulation of discrete event systems, design of a model of a selected device, analysis and software verification of the designed models.

Basic bibliography:

1. Cassandras C. G., Lafortune S.: Introduction to Discrete Event Systems Second Edition, Springer US 2008

2. A. Zimmermann.: Stochastic Discrete Event Systems Modeling, Evaluation, Applications, Springer-Verlag Berlin Heidelberg 2008

Additional bibliography:

1. Update 2017: K. Walas and A. Kasinski.: Discrete event controller for urban obstacles negotiation with walking robot, in IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2012, pp. 181?186.

2. Update 2017: G. A. D. Lopes, B. Kersbergen, T. J. J. van den Boom, B. De Schutter, R. Babuska, IEEE TRANSACTIONS ON ROBOTICS, VOL. 30, NO. 3, JUNE 2014

3. Synthesising robust and optimal parameters for cardiac pacemakers using symbolic and evolutionary computation techniques. Kwiatkowska, Mereacre, Paoletti and Patane, HSB?16

4. M. Kwiatkowska, A. Mereacre, N. Paoletti, A. Patane, Synthesising Robust and Optimal Parameters for Cardiac Pacemakers Using Symbolic and Evolutionary Computation Techniques, Hybrid Systems Biology: Fourth International Workshop, HSB 2015, Madrid, Spain, September 4-5, 2015

Result of average student's workload

Activity	Time (working hours)				
1. Lectures	45				
2. Projects	15				
3. Tutorials	9				
4. Preparation to the projects	46				
Student's workload					
Source of workload	hours	ECTS			
Total workload	115	5			
Contact hours	69	3			
Practical activities	46	2			